

BOUNDED SOLUTIONS FOR AN INCOMPLETE CAUCHY PROBLEM INVOLVING A NON-CONVEX FUNCTION*

Gheorghe Moroşanu[†] Cristian Vladimirescu[‡]

*Dedicated with friendship and appreciation to
 Professor Biagio Ricceri on the occasion
 of his 70th anniversary*

Abstract

Consider in a real Hilbert space $(H, (\cdot, \cdot), \|\cdot\|)$ the following incomplete Cauchy problem,

$$(ICP) \quad \begin{cases} u''(t) = \nabla \phi(u(t)), & t \geq 0, & (E) \\ u(0) = u_0, & & (IC) \end{cases}$$

where $u_0 \in H$ is a given initial state, and $\phi : H \rightarrow \mathbb{R}$ is a C^1 , non-convex function (preferably quasiconvex, as explained below). We call (ICP) an *incomplete Cauchy problem* because the usual additional Cauchy condition $u'(0) = v_0$ is missing. In this paper, we establish sufficient conditions on the non-convex function ϕ guaranteeing the existence of bounded solutions on $[0, \infty)$ of (ICP) for any $u_0 \in H$.

Keywords: second order differential equation, gradient of a C^1 function, bounded solutions.

MSC: 34G20, 26B25.

* Accepted for publication on December 4, 2025

[†] gheorghe.morosanu@ubbcluj.ro, Department of Mathematics, Babeş-Bolyai University, Cluj-Napoca, Romania & Academy of Romanian Scientists, Bucharest

[‡] cristian.vladimirescu@edu.ucv.ro, Computers and Information Technology Department, University of Craiova, Craiova, Romania

1 Introduction

First of all, we recall that the existence of bounded solutions for the problem (*ICP*) formulated in our abstract above has been proved long ago in the case when $\phi : H \rightarrow (-\infty, \infty]$ is a proper (i.e., not identically $+\infty$), lower semicontinuous, convex function with a nonempty set of minimum points (see [1, Chap. V, p. 315]). More precisely, in this case, for any $u_0 \in \overline{D(\phi)}$, there exists a unique bounded solution of problem (*ICP*) with the subdifferential $\partial\phi$ instead of $\nabla\phi$. That is why here we concentrate our attention on the case when ϕ is non-convex. By showing the existence of bounded solutions on $[0, \infty)$ for (*ICP*), we legitimize the existing results on the asymptotic behavior of the solutions to equation (*E*) as $t \rightarrow \infty$, where ϕ is a quasiconvex function (i.e., its level sets $\{x \in H; \phi(x) \leq \alpha\}$, $\alpha \in \mathbb{R}$, are convex) (see [5], [6]).

Specifically, in this paper we provide an answer to the long standing open problem concerning the existence of bounded solutions for the problem (*ICP*) with a C^1 function ϕ in two cases:

1. the gradient $\nabla\phi$ is a Lipschitz operator;
2. the function ϕ satisfies

$$a|v|^2 \leq \phi(v) \leq b|v|^2, \quad \forall v \in H, \quad (1)$$

where $0 < a < b < \infty$ are given numbers.

2 The case when ϕ is a C^1 function with $\nabla\phi$ Lipschitzian

In this case we have the following result:

Theorem 1. *Assume that $\phi : H \rightarrow \mathbb{R}$ is differentiable and $\nabla\phi$ is a Lipschitz operator on H . Then for all $u_0, v_0 \in H$ there exists a unique function $u \in C^2([0, \infty); H)$ satisfying equation (*E*) on $[0, \infty)$ and the Cauchy conditions $u(0) = u_0, u'(0) = v_0$.*

Proof. Using the substitution $v(t) = u'(t)$ we are led to the following Cauchy problem in the product space $X := H \times H$ equipped with the usual scalar product and norm:

$$\begin{cases} \frac{d}{dt}(u, v) = (v, \nabla\phi(u)), & t \geq 0, \\ (u(0), v(0)) = (u_0, v_0). \end{cases}$$

Let T be an arbitrary but fixed positive number. By applying Banach's Contraction Principle, we easily derive the existence of a unique solution $(u, v) \in C^1([0, T]; X)$ of the above problem considered on the interval $[0, T]$. Of course, this solution can uniquely be extended to the whole half axis $[0, \infty)$. So $u = u(t)$ belongs to $C^2([0, \infty); H)$ and it is the unique solution of equation (E) satisfying the Cauchy conditions $u(0) = u_0$, $u'(0) = v_0$. Hence, the conclusion of Theorem 1 holds true. \square

2.1 Existence of bounded solutions on $[0, \infty)$ for (ICP)

In the context of Theorem 1, we need to identify additional conditions on ϕ that guarantee the boundedness of $u = u(t)$ on $[0, \infty)$. Such situations are possible. In what follows, we identify a class of C^1 functions ϕ with Lipschitzian gradients such that for every $u_0 \in H$, $u = u(t; u_0, v_0)$ in Theorem 1 be bounded on $[0, \infty)$ for some $v_0 \in H$.

For the moment, let us consider for example the function $\phi : H \rightarrow \mathbb{R}$ defined by

$$\phi(v) = \frac{|v|^2}{1 + |v|^2}, \quad v \in H.$$

This function is not convex (but is quasiconvex), and its Fréchet derivative is given by

$$\nabla \phi(v) = \frac{2}{(1 + |v|^2)^2} v, \quad v \in H.$$

Furthermore, by an elementary computation it follows that $\nabla \phi : H \rightarrow H$ is a Lipschitz operator. Therefore, according to Theorem 1 above, for every $u_0, v_0 \in H$, there exists a unique function $u = u(t; u_0, v_0) \in C^2([0, \infty); H)$ satisfying equation (E) and the Cauchy conditions $u(0) = u_0$ and $u'(0) = v_0$. According to [3, 1177–1178], for every $u_0 \in H$, $u(t; u_0, v_0)$ is bounded on $[0, \infty)$ for some $v_0 \in H$.

Indeed, if we multiply equation (E) by $u'(t)$ we get

$$\frac{1}{2} \frac{d}{dt} |u'(t)|^2 = \frac{d}{dt} \phi(u(t)), \quad t \geq 0,$$

or, equivalently,

$$\frac{1}{2} |u'(t)|^2 = \phi(u(t)) + C, \quad t \geq 0,$$

where C is a real constant. We choose $v_0 = u'(0)$ such that $C = 0$, and

consider the following related Cauchy problem in H , denoted (CP) ,

$$\begin{cases} u'(t) = -\frac{\sqrt{2}}{\sqrt{1+|u(t)|^2}}u(t), & t \geq 0, \\ u(0) = u_0. \end{cases} \quad (2)$$

It is easily seen that the operator $P : H \rightarrow H$ defined by

$$Pv = -\frac{\sqrt{2}}{\sqrt{1+|v|^2}}v, \quad v \in H$$

is Lipschitzian. Therefore the above problem (CP) has a unique solution $u = u(t, u_0, v_0) \in C^\infty([0, \infty); H)$, with v_0 chosen above (by applying Banach's Contraction Principle in the space $C([0, T]; H)$, $T > 0$, equipped with a Bielecki norm, with extension to $[0, \infty)$).

Now, multiplying equation (2) by $u(t)$, we find

$$\frac{d}{dt}|u(t)|^2 \leq 0, \quad t \geq 0,$$

so $|u(t)| \leq |u_0|$, $t \geq 0$. Hence $u = u(t, u_0, v_0)$ is bounded on $[0, \infty)$. In fact this u satisfies (ICP) . Indeed, if we differentiate the equation

$$\sqrt{1+|u|^2}u' + \sqrt{2}u = 0, \quad t \geq 0,$$

derived from (2), we obtain

$$\frac{(u, u')}{\sqrt{1+|u|^2}}u' + \sqrt{1+|u|^2}u'' = -\sqrt{2}u', \quad t \geq 0. \quad (3)$$

Using again (2) we obtain

$$(u, u') = -\frac{\sqrt{2}|u|^2}{\sqrt{1+|u|^2}}, \quad (4)$$

and so by (3) and (4) we derive

$$u'' = \frac{2}{(1+|u|^2)^2}u, \quad t \geq 0,$$

hence u satisfies equation (E) . Therefore, the function $\phi : H \rightarrow \mathbb{R}$,

$$\phi(v) = \frac{|v|^2}{1+|v|^2}, \quad v \in H,$$

is a good example for the existence of bounded solutions on $[0, \infty)$ for problem (ICP).

Note that the same example was considered in [4] in the particular case $H = \mathbb{R}$ which allows using elementary student level arguments.

Now, for $\lambda, \mu > 0$, define $\phi_{\lambda\mu} : H \rightarrow \mathbb{R}$ by

$$\phi_{\lambda\mu}(v) = \frac{\lambda|v|^2}{1 + \mu|v|^2}, \quad v \in H.$$

It is easily seen (by using arguments similar to those corresponding to the case $\lambda = \mu = 1$) that problem (ICP) with $\phi = \phi_{\lambda\mu}$ has bounded solutions on $[0, \infty)$ for all $\lambda > 0, \mu > 0$. Therefore, we have a class of functions $\{\phi_{\lambda\mu}, \lambda, \mu > 0\}$ generating bounded solutions for (ICP). Many other classes of such functions could also be considered for applications.

3 The case when ϕ is a C^1 function satisfying condition (1)

In this case we have the following result:

Theorem 2. *If $\phi : H \rightarrow \mathbb{R}$ is a C^1 function satisfying condition (1) above, then problem (ICP) has a solution bounded on $[0, \infty)$.*

Proof. First of all, it follows by condition (1) that $\phi(0) = 0$ and $\phi = \phi(v)$ attains its global minimum at $v = 0$, so $\nabla\phi(0) = 0$. Therefore, in this case problem (ICP) admits the null solution. In what follows we will assume that $u_0 \neq 0$.

Consider the Sobolev space $X = W^{1,2}((0, \infty); H)$, i.e., the space of all $w \in L^2((0, \infty); H)$ with derivatives $w' \in L^2((0, \infty); H)$, equipped with the inner product

$$((w_1, w_2)) = \int_0^\infty (w_1(t), w_2(t)) dt + \int_0^\infty (w_1'(t), w_2'(t)) dt, \quad \forall w_1, w_2 \in X,$$

and the corresponding norm

$$\|w\| = \left(\int_0^\infty |w(t)|^2 dt + \int_0^\infty |w'(t)|^2 dt \right)^{1/2}, \quad \forall w \in X,$$

so $(X, ((\cdot, \cdot)), \|\cdot\|)$ is a real Hilbert space.

Now, consider the subspace $X_0 = W_0^{1,2}((0, \infty); H)$, which is defined as the closure of $C_0^\infty((0, \infty); H)$ in X . In other words, $X_0 = W_0^{1,2}((0, \infty); H)$

consists of all $w \in W^{1,2}((0, \infty); H)$ with $w(0) = 0$, being a Hilbert subspace of $X = W^{1,2}((0, \infty); H)$ with the same scalar product and norm.

Now, let us define the function $F : X_0 \rightarrow \mathbb{R}$ by

$$F(w) = \frac{1}{2} \int_0^\infty |w'(t) - e^{-t}u_0|^2 dt + \int_0^\infty \phi(w(t) + e^{-t}u_0) dt, \quad w \in X_0.$$

According to our condition (1), F is well defined on X_0 and coercive (i.e., $F(w)$ converges to ∞ as $\|w\| \rightarrow \infty$).

By the coercivity of F it follows that $\forall M > 0$ the set $\{w \in X_0; F(w) < M\}$ is bounded in X_0 . Let (w_n) be a minimizing sequence in X_0 satisfying

$$\inf_{X_0} F \leq F(w_n) < \inf_{X_0} F + \frac{1}{n}, \quad \forall n \in \mathbb{N}. \quad (5)$$

Then (w_n) is bounded in X_0 so, as X_0 is a Hilbert space (hence reflexive), one can extract a subsequence, again denoted (w_n) , which converges weakly in X_0 to some $\tilde{u} \in X_0$.

On the other hand, as w_n converges weakly to \tilde{u} in X_0 , it follows that w_n converges weakly in $L^2((0, \infty); H)$ (to \tilde{u}), and w'_n also converges weakly in $L^2((0, \infty); H)$ to the derivative \tilde{u}' . Let us explain this in detail for completeness. Denote by z the weak limit of w'_n in $L^2((0, \infty); H)$. Notice that for all $n \in \mathbb{N}$, $w = \psi(t)\zeta$ with $\psi \in C_0^\infty(0, \infty)$ and $\zeta \in H$, we have

$$\int_0^\infty (w'_n(t), \zeta) \psi(t) dt = - \int_0^\infty (w_n(t), \zeta) \psi'(t) dt,$$

which implies by passing to limit as $n \rightarrow \infty$,

$$\int_0^\infty (z(t), \zeta) \psi(t) dt = - \int_0^\infty (\tilde{u}(t), \zeta) \psi'(t) dt,$$

and so

$$\int_0^\infty (z(t), \zeta) \psi(t) dt = \int_0^\infty (\tilde{u}'(t), \zeta) \psi(t) dt,$$

for all $\zeta \in H$ and $\psi \in C_0^\infty(0, \infty)$. Hence $z = \tilde{u}'$ and consequently $w'_n \rightarrow \tilde{u}'$ weakly in $L^2((0, \infty); H)$, as asserted.

On the other hand, for $T > 0$ arbitrary but fixed, the sequence (w_n) is bounded in $C([0, T]; H)$ and equi-continuous on $[0, T]$, as one can easily deduce from

$$w_n(t) = \int_0^t w'_n(s) ds, \quad n \in \mathbb{N}.$$

So by the Arzelà-Ascoli Criterion w_n converges to \tilde{u} in $C([0, T]; H)$. Since $T > 0$ was arbitrary and $\phi \in C^1$, we have

$$\lim_{n \rightarrow \infty} \phi(w_n(t) + e^{-t}u_0) = \phi(\tilde{u}(t) + e^{-t}u_0),$$

uniformly on every interval $[0, T]$, where $t \rightarrow \phi(\tilde{u}(t) + e^{-t}u_0)$ belongs to $C([0, \infty); \mathbb{R}) \cap L^1((0, \infty); \mathbb{R})$.

Moreover, for every $T \in (0, \infty)$, we have

$$\liminf_{n \rightarrow \infty} \int_0^\infty \phi(w_n(t) + e^{-t}u_0) dt \geq \int_0^T \phi(\tilde{u}(t) + e^{-t}u_0) dt,$$

which implies

$$\liminf_{n \rightarrow \infty} \int_0^\infty \phi(w_n(t) + e^{-t}u_0) dt \geq \int_0^\infty \phi(\tilde{u}(t) + e^{-t}u_0) dt.$$

On the other hand, as $w'_n \rightarrow \tilde{u}'$ weakly in $L^2((0, \infty); H)$, we have

$$\liminf_{n \rightarrow \infty} \int_0^\infty |w'_n(t) - e^{-t}u_0|^2 dt \geq \int_0^\infty |\tilde{u}'(t) - e^{-t}u_0|^2 dt.$$

Therefore, $F(\tilde{u}) \leq \liminf_{n \rightarrow \infty} F(w_n)$. In fact, taking into account (5), we can conclude that $\inf_{X_0} F = \lim_{n \rightarrow \infty} F(w_n) = F(\tilde{u})$. As \tilde{u} is a minimum point of F on X_0 , we have

$$\nabla F(\tilde{u}) = 0. \quad (6)$$

Now, for $\lambda > 0$ and $v \in X_0$, we have

$$\begin{aligned} \frac{F(\tilde{u} + \lambda v) - F(\tilde{u})}{\lambda} &= \frac{1}{2\lambda} \int_0^\infty (|\tilde{u}'(t) - e^{-t}u_0 + \lambda v'(t)|^2 - |\tilde{u}'(t) - e^{-t}u_0|^2) dt + \\ &\quad \frac{1}{\lambda} \int_0^\infty (\phi(\tilde{u}(t) + e^{-t}u_0 + \lambda v(t)) - \phi(\tilde{u}(t) + e^{-t}u_0)) dt. \end{aligned}$$

Hence, for $\lambda \rightarrow 0^+$ we get (see also equation (6) above)

$$0 = \int_0^\infty (\tilde{u}'(t) - e^{-t}u_0, v'(t)) dt + \int_0^\infty (\nabla \phi(\tilde{u}(t) + e^{-t}u_0), v(t)) dt,$$

for all $v \in C_0^\infty((0, \infty); H)$. Therefore, choosing in the last equation $v(t) = \alpha(t)\xi$, with $\alpha \in C_0^\infty(0, \infty)$ and $\xi \in H$, we get

$$\begin{cases} -\tilde{u}''(t) - e^{-t}u_0 + \nabla \phi(\tilde{u}(t) + e^{-t}u_0) = 0, & t \geq 0, \\ \tilde{u} \in X_0, \end{cases}$$

hence $u(t) = \tilde{u}(t) + e^{-t}u_0$ satisfies problem (ICP). Note that both the functions $f(t) = |u(t)|^2$, $f'(t) = 2((u(t), u'(t)))$ belong to $L^1((0, \infty); \mathbb{R})$. It follows from

$$f(t) = |u_0|^2 + \int_0^t f'(s) ds$$

that $\sup_{t \geq 0} |u(t)| < \infty$, so problem (ICP) has a solution bounded on $[0, \infty)$. \square

Remark 1. Notice that in Theorem 2 we did not assume that ϕ is a quasiconvex function, but this situation is not excluded. One can say that in Theorem 2 the function ϕ is almost convex, but not necessarily convex.

3.1 Graphical representations in the case $H = \mathbb{R}$

We notice that in the case $H = \mathbb{R}$ there are infinitely many quasiconvex C^1 functions $y = \phi(v)$ satisfying condition (1) above, that may be alternatively convex and concave on subintervals, i.e., their graphs are smooth wavy curves situated in the region between the graphs of the functions $y = a|v|^2 = av^2$ and $y = b|v|^2 = bv^2$, as illustrated in Figures 1–3 below, wherein the plottings were obtained using Matlab.

Example 1. Consider the functions $g, h : \mathbb{R} \rightarrow \mathbb{R}$, $g(v) = 0.1v^2$, $h(v) = 0.02v^2$, and the function $\phi : \mathbb{R} \rightarrow \mathbb{R}$ defined by

$$\phi(v) = \begin{cases} h(v), & 0 \leq v \leq 2, \\ (1 - \theta(v))h(v) + \theta(v)F(v), & v \geq 2, \\ \phi(-v), & v \leq 0, \end{cases}$$

where

$$\begin{aligned} \theta(v) &= s\left(\frac{v}{2} - 1\right), \quad v \in \mathbb{R}, \\ s(t) &= \begin{cases} 0, & t \leq 0, \\ 3t^2 - 2t^3, & 0 < t < 1, \\ 1, & t \geq 1, \end{cases} \end{aligned}$$

and

$$F(v) = 0.056v^2 + 0.036 \sin(4v), \quad v \in \mathbb{R}.$$

Then ϕ is quasiconvex, of class $C^1(\mathbb{R})$, ϕ' is Lipschitzian, and its graph is plotted in Figure 1 below on a time interval.

Example 2. We take now the functions $g, h : \mathbb{R} \rightarrow \mathbb{R}$, $g(v) = 0.1v^2$, $h(v) = 0.01v^2$, and $\phi : \mathbb{R} \rightarrow \mathbb{R}$,

$$\phi(v) = \begin{cases} g(v) - (g(v) - h(v))S_1(v), & v \in (-\infty, -5), \\ g(v), & v \in [-5, 0], \\ h(v), & v \in [0, 6], \\ h(v) + (g(v) - h(v))S_2(v), & v \in (6, \infty), \end{cases}$$

where

$$S_1(v) = 0.5(1 - \exp(-2(-5 - v)))^2(1 + 0.4 \sin(1.5(-5 - v))), \quad v \in \mathbb{R},$$

$$S_2(v) = 0.25(1 - \exp(-2(v - 6)))^2(1 + 0.3 \sin(1.5(v - 6))), \quad v \in \mathbb{R}.$$

We easily infer that ϕ is of class $C^1(\mathbb{R})$ and ϕ' is Lipschitzian. The plotting of the graph of ϕ on a time interval is given in Figure 2 below.

Example 3. Another example is represented by the functions $g, h : \mathbb{R} \rightarrow \mathbb{R}$, $g(v) = 0.1v^2$, $h(v) = 0.01v^2$, and $\phi : \mathbb{R} \rightarrow \mathbb{R}$,

$$\phi(v) = \begin{cases} h(v) + (g(v) - h(v))S_1(v), & v \in (-\infty, -6), \\ h(v), & v \in [-6, 0], \\ g(v), & v \in [0, 5], \\ g(v) - (g(v) - h(v))S_2(v), & v \in (5, \infty), \end{cases}$$

where

$$S_1(v) = 0.25(1 - \exp(-2(-6 - v)))^2(1 + 0.4 \sin(1.5(-6 - v))), \quad v \in \mathbb{R},$$

$$S_2(v) = 0.7(1 - \exp(-2(v - 5)))^2(1 + 0.3 \sin(1.5(v - 5))), \quad v \in \mathbb{R}.$$

Then ϕ is of class $C^1(\mathbb{R})$ and ϕ' is Lipschitzian, the plotting of the graph of ϕ on a time interval being provided in Figure 3 below.

4 Conclusion

In this paper, we have identified classes of non-convex C^1 functions ϕ such that the problem given in (ICP) has bounded solutions on $[0, \infty)$. Thus we have legitimized the efforts in [2], [5], [6] towards establishing results on the asymptotic behavior of the *bounded solutions* to problem (ICP) as $t \rightarrow \infty$.

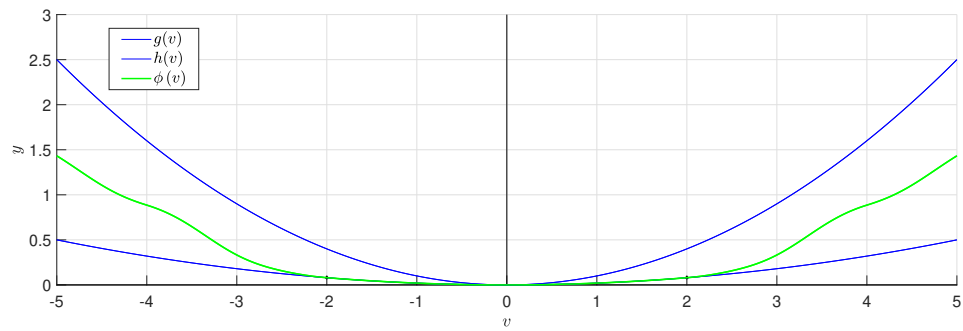


Figure 1: The graph of the function ϕ defined in Example 1

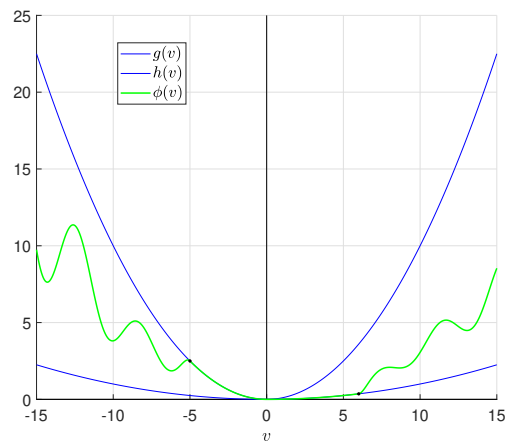


Figure 2: The graph of the function ϕ defined in Example 2

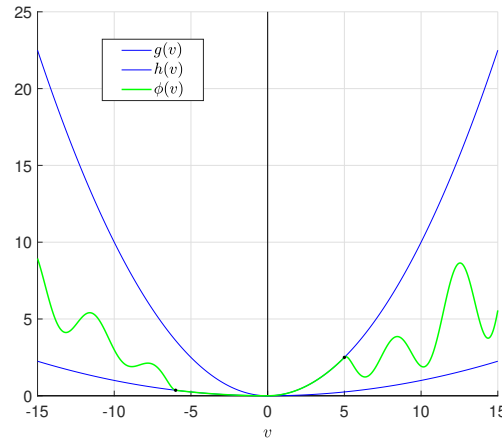


Figure 3: The graph of the function ϕ defined in Example 3

Acknowledgements. Gheorghe Moroşanu would like to thank Professor Biagio Ricceri for the fruitful discussions that led to the final version of this paper.

I also thank the co-author for the discussions we had and for inserting the three clarifying figures in Section 3.

Many thanks are also due to Dr. Viorica V. Motreanu, my former PhD student, for checking the whole paper and correcting some minor errors.

Last but not least, I would like to thank Professor Daniel Drimbe from the University of Iowa in Iowa City (IA, USA) for hospitality and helpful conversations on the topic of this article during my visit to the University of Iowa in September-October 2025.

References

- [1] V. Barbu, *Nonlinear Semigroups and Differential Equations in Banach Spaces*, Noordhoff, Leyden, 1976.
- [2] H. Khatibzadeh and G. Moroşanu, Asymptotic behavior of solutions to a second-order gradient equation of pseudo-convex type, *J. Convex Anal.* 26 (2019), 1175-1186.
- [3] G. Moroşanu, *Nonlinear Evolution Equations and Applications*, D. Reidel, Dordrecht - Boston - Lancaster - Tokyo, 1988.

- [4] G. Moroşanu, On second-order differential equations associated with gradients of pseudoconvex functions, *Gazeta Matematică, Ser. A* XXXIII (CXII) (2015), 3-4.
- [5] R. Qazi, M. Rahimi Piranfar and H. Khatibzadeh, On the convergence of solutions to an incomplete Cauchy problem governed by a quasi-convex function and a quasi-nonexpansive operator, *J. Fixed Point Theory Appl.* 27 (2025), 4.
- [6] M. Rahimi Piranfar and H. Khatibzadeh, Long-time behavior of a gradient system governed by a quasiconvex function, *J. Optim. Theory Appl.* 188 (2021), 169-191.